

Spin-1 spin-orbit- and Rabi-coupled Bose–Einstein condensate solver^{☆,☆☆}

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ABSTRACT

We present OpenMP versions of FORTRAN programs for solving the Gross–Pitaevskii equation for a harmonically trapped three-component spin-1 spinor Bose–Einstein condensate (BEC) in one (1D) and two (2D) spatial dimensions with or without spin-orbit (SO) and Rabi couplings. Several different forms of SO coupling are included in the programs. We use the split-step Crank–Nicolson discretization for imaginary- and real-time propagation to calculate stationary states and BEC dynamics, respectively. The imaginary-time propagation programs calculate the lowest-energy stationary state. The real-time propagation programs can be used to study the dynamics. The simulation input parameters are provided at the beginning of each program. The programs propagate the condensate wave function and calculate several relevant physical quantities. Outputs of the programs include the wave function, energy, root-mean-square sizes, different density profiles (linear density for the 1D program, linear and surface densities for the 2D program). The imaginary- or real-time propagation can start with an analytic wave function or a pre-calculated numerical wave function. The imaginary-time propagation usually starts with an analytic wave function, while the real-time propagation is often initiated with the previously calculated converged imaginary-time wave function.

Program summary

Program title: BEC-GP-SPINOR, consisting of: BEC-GP-SPINOR-OMP package, containing programs spin-SO-imre1d-omp.f90 and spin-SO-imre2d-omp.f90, with util.f90.

CPC Library link to program files: <https://doi.org/10.17632/j3wr4wn946.1>

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Programming language: OpenMP FORTRAN. The FORTRAN programs are tested with the GNU, Intel, PGI, and Oracle compiler.

Nature of problem: The present Open Multi-Processing (OpenMP) FORTRAN programs solve the time-dependent nonlinear partial differential Gross–Pitaevskii (GP) equation for a trapped spinor Bose–Einstein condensate, with or without spin-orbit coupling, in one and two spatial dimensions.

Solution method: We employ the split-step Crank–Nicolson rule to discretize the time-dependent GP equation in space and time. The discretized equation is then solved by imaginary- or real-time propagation, employing adequately small space and time steps, to yield the solution of stationary and non-stationary problems, respectively.

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1. Introduction

Previously published FORTRAN [1] and C [2] programs are now popular tools for studying the properties of a Bose–Einstein condensate (BEC) by solving the Gross–Pitaevskii (GP) equation and are enjoying widespread use. These programs have later been extended to the more complex scenario of dipolar atoms [3] and of rotating BECs [4]. The OpenMP [5,6] and CUDA [7–9] version of these programs, designed to make these faster and more efficient in multi-core computers, are also available.

There has been great interest in the studies of spinor BECs using the GP equation after the experimental observation of the same [10,11]. Later, it has been possible to introduce an artificial synthetic spin–orbit (SO) coupling by Raman lasers that coherently couple the spin-component states in a pseudo spin-1/2 [12,13] and spin-1 [14] spinor BEC. In this paper, we present new OpenMP FORTRAN programs to solve the GP equation for a three-component spin-1 spinor quasi-one-dimensional (quasi-1D) and quasi-two-dimensional (quasi-2D) BECs [15] with [16,17] or without [18,19] SO and associated Rabi couplings, based on our earlier programs [5,6]. The GP equation for an SO-coupled three-component spin-1 trapped BEC is conveniently solved by the imaginary- and real-time propagation methods. We provide combined imaginary- and real-time programs in one and two spatial dimensions. The present imaginary-time programs already involve complex variables and are hence combined together with the real-time programs, requiring complex algebra. The choice of the type of propagation (imaginary- or real-time) is made through an input parameter. The imaginary-time approach should be used to solve the GP equation for stationary states. A subsequent study of the non-stationary dynamics of the BEC should be done using the real-time propagation using the imaginary-time wave function as the initial state. We use the split-step Crank–Nicolson scheme for solving the GP equation, as in Refs. [1,2].

In Section 2 we present the GP equation for a spin-1 spinor BEC in a trap. The mean-field model and a general scheme for its numerical solution are considered for both quasi-1D and quasi-2D traps. The details about the computer programs, and their input parameters, output files, etc. are given in Section 3. The numerical method and results are given in Section 4, where we illustrate the results for density and energy by employing the imaginary-time propagation for different interaction strengths (nonlinearities). The stability of the density profiles is demonstrated in real-time propagation using the corresponding converged solution obtained by the imaginary time propagation as the initial state. Finally, a brief summary is given in Section 5. Technical and mathematical details of this investigation are presented in two Appendices. A novel numerical procedure applied in this study is given in Appendix A. Useful analytic variational and Thomas–Fermi (TF) approximations are developed in the Supplementary material.

2. The Gross–Pitaevskii equation for a spin-1 condensate

In the mean-field approximation a quasi-1D or quasi-2D SO and Rabi coupled spin-1 ($F = 1$) BEC is described by the following set of three coupled GP equations, for N atoms of mass \tilde{m} each, in dimensionless form, for the spin components $F_z = \pm 1, 0$ [18–20]

$$i\partial_t \psi_{\pm 1}(\mathbf{r}) = \left[-\frac{1}{2} \nabla^2 + V(\mathbf{r}) + c_0 \rho + c_2 (\rho_{\pm 1} - \rho_{\mp 1} + \rho_0) \right] \psi_{\pm 1}(\mathbf{r}) + \{c_2 \psi_0^2(\mathbf{r}) \psi_{\mp 1}^*(\mathbf{r})\} + \frac{\Omega}{\sqrt{2}} \psi_0(\mathbf{r}) + \gamma f_{\pm 1}, \quad (1)$$

$$i\partial_t \psi_0(\mathbf{r}) = \left[-\frac{1}{2} \nabla^2 + V(\mathbf{r}) + c_0 \rho + c_2 (\rho_{+1} + \rho_{-1}) \right] \psi_0(\mathbf{r}) + \{2c_2 \psi_{+1}(\mathbf{r}) \psi_{-1}(\mathbf{r}) \psi_0^*(\mathbf{r})\} + \frac{\Omega}{\sqrt{2}} \sum_{j=+1,-1} \psi_j(\mathbf{r}) + \gamma g, \quad (2)$$

where $\rho_j = |\psi_j|^2$ are the densities of components $j = \pm 1, 0$, and $\rho(\mathbf{r}) = \sum \rho_j(\mathbf{r})$ is the total density, $V(\mathbf{r})$ is the confining trap, ∂_t ($\partial_{\mathbf{r}} \equiv \{\partial_x, \partial_y, \partial_z\}$) is the partial time (space) derivative, and Ω (γ) is the strength of Rabi (SO) coupling. The SO coupling is a space derivative coupling described by the functions f and g , the details of which are given below. For brevity, the time dependence of the wave functions is not explicitly shown in Eqs. (1) and (2). In 1D, $\mathbf{r} = x$, $\nabla^2 = \partial_x^2 = \partial^2/\partial x^2$, in 2D, $\mathbf{r} = \{x, y\}$, $\nabla^2 = \partial_x^2 + \partial_y^2$, and in 3D, $\mathbf{r} = \{x, y, z\}$, $\nabla^2 = \partial_x^2 + \partial_y^2 + \partial_z^2$. In 3D, distances are expressed in units of the harmonic oscillator length $l \equiv \sqrt{\hbar/m\omega}$, density ρ_j in units of l^{-3} and time in units of ω^{-1} , where $\omega = \omega_x$ is the x -axis trapping frequency. The potential is $V(\mathbf{r}) = (x^2 + \kappa^2 y^2 + \beta^2 z^2)/2$, where the trap aspect ratios are $\kappa = \omega_y/\omega$ and $\beta = \omega_z/\omega$. The dimensionless nonlinearities are $c_i = 4\pi N \mathcal{A}_i$, $i = 0, 2$, where $\mathcal{A}_0 = (a_0 + 2a_2)/3l$, $\mathcal{A}_2 = (a_2 - a_0)/3l$, with a_0 and a_2 being the scattering lengths in the total spin channels 0 and 2, respectively. For a pancake-shaped trap, with the strong trapping in z direction ($\beta \gg 1, \kappa$), a set of quasi-2D [15] equations can be obtained with $c_i = 2\sqrt{2\pi} \beta N \mathcal{A}_i$, with $V(\mathbf{r}) = (x^2 + \kappa^2 y^2)/2$. For a cigar-shaped trap, with the strong trapping in y and z directions ($\beta, \kappa \gg 1$), a set of quasi-1D [15] equations can be obtained with $c_i = 2\sqrt{\kappa} \beta N \mathcal{A}_i$, where $V(\mathbf{r}) = x^2/2$. In the following we will take $\kappa = 1$ and $V(\mathbf{r}) = \mathbf{r}^2/2$ in both 1D and 2D. In the programs the parameter κ in the potential is set to unity, but a different value can be introduced easily if needed.

In the presence of the SO coupling [16,17], we consider below the SO-coupling contributions $\gamma f_{\pm 1}$ and γg of Eqs. (1) and (2) in different cases. In 1D we consider three possible SO couplings in the Hamiltonian: $\gamma p_x \Sigma_x$, $\gamma p_x \Sigma_y$, and $\gamma p_x \Sigma_z$, where $p_x = -i\partial_x$ is the momentum operator and Σ_x , Σ_y and Σ_z are the irreducible representations of the x , y and z components of the spin-1 matrix Σ , with components

$$\Sigma_x = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, \quad \Sigma_y = \frac{i}{\sqrt{2}} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}, \quad \Sigma_z = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}. \quad (3)$$

For the SO coupling $\gamma p_x \Sigma_x$ [21,22] in 1D, the SO coupling terms in Eqs. (1), (2) are $\gamma f_{\pm 1} = -i\tilde{\gamma} \partial_x \psi_0(\mathbf{r})$ and $\gamma g = -i\tilde{\gamma} [\partial_x \psi_{+1}(\mathbf{r}) + \partial_x \psi_{-1}(\mathbf{r})]$, respectively, where $\tilde{\gamma} = \gamma/\sqrt{2}$. For the SO coupling $\gamma p_x \Sigma_y$ they are $\gamma f_{\pm 1} = \mp i\tilde{\gamma} \partial_x \psi_0(\mathbf{r})$ and $\gamma g = i\tilde{\gamma} [\partial_x \psi_{+1}(\mathbf{r}) - \partial_x \psi_{-1}(\mathbf{r})]$, respectively. For the SO coupling $\gamma p_x \Sigma_z$ they are [22] $\gamma f_{\pm 1} = \mp i\tilde{\gamma} \partial_x \psi_{\pm 1}(\mathbf{r})$ and $\gamma g = 0$, respectively.

In 2D we consider the general SO coupling term in the form $\gamma(\eta p_y \Sigma_x - p_x \Sigma_y)$, where $\eta = 1, -1$ and 0 for Rashba [23], Dresselhaus [24] and an equal mixture of Rashba and Dresselhaus SO couplings. In Eqs. (1), (2), the Rashba, Dresselhaus and an equal

mixture of Rashba and Dresselhaus coupling terms in 2D are $\gamma f_{\pm 1} = -i\tilde{\gamma} \left[\eta \partial_y \psi_0(\mathbf{r}) \pm i \partial_x \psi_0(\mathbf{r}) \right]$ and $\gamma g = -i\tilde{\gamma} \left[-i \partial_x \psi_{+1}(\mathbf{r}) + i \partial_x \psi_{-1}(\mathbf{r}) + \eta \partial_y \psi_{+1}(\mathbf{r}) + \eta \partial_y \psi_{-1}(\mathbf{r}) \right]$.

The normalization and magnetization (m) conditions are given by

$$\int \rho(\mathbf{r}) d\mathbf{r} = 1, \quad \text{and} \quad \int [\rho_{+1}(\mathbf{r}) - \rho_{-1}(\mathbf{r})] d\mathbf{r} = m. \quad (4)$$

Condition (4) is useful to solve the problem for a fixed normalization when magnetization m along z direction is conserved, e.g., when the Hamiltonian commutes with spin-matrix Σ_z . However, in the presence of an SO coupling, that does not commute with Σ_z , magnetization is not conserved due to spin mixing dynamics involving spin-up and down states. In that case, time propagation is performed by imposing only the condition of conservation of normalization without fixing the magnetization during time propagation [25] and it leads to the result for the dynamically stable stationary state with a magnetization determined by the parameters of the model, which could often be zero. In this context, it should be noted that in experiments it is not possible to fix a preassigned value to magnetization, which is not a constant of motion.

The energy functional of the system is [18,19]

$$\begin{aligned} E = \frac{1}{2} \int d\mathbf{r} \left\{ \sum_j |\nabla_{\mathbf{r}} \psi_j|^2 + 2V(\mathbf{r})\rho + c_0\rho^2 \right. \\ \left. + c_2 \left[\rho_{+1}^2 + \rho_{-1}^2 + 2 \left(\rho_{+1}\rho_0 + \rho_{-1}\rho_0 - \rho_{+1}\rho_{-1} + \psi_{-1}^* \psi_0^2 \psi_{+1}^* + \psi_{-1} \psi_0^{*2} \psi_{+1} \right) \right] \right. \\ \left. + 2 \frac{\Omega}{\sqrt{2}} \left[(\psi_{+1}^* + \psi_{-1}^*) \psi_0 + \psi_0^* (\psi_{+1} + \psi_{-1}) \right] + 2\gamma \left[\psi_{+1}^* f_{+1} + \psi_{-1}^* f_{-1} + \psi_0^* g \right] \right\}. \quad (5) \end{aligned}$$

3. Details about the programs

We use the split time step Crank–Nicolson discretization rule for solving the GP equations (1) and (2), including the appropriate SO and Rabi couplings with strengths γ and Ω , respectively. This approach has been elaborated in detail in Ref. [1]. An initial (known) wave function at time t is used to calculate the wave function at time $t + \Delta$, after a small time step Δ . The advantage of this approach lies in the fact that different terms on the right-hand-side of Eqs. (1) and (2) can be treated successively. For example, the spatial derivative term involving $\nabla_{\mathbf{r}}$ can be treated independently of the nonlinear interaction terms and also of the SO and Rabi coupling terms. The terms in the square brackets of Eqs. (1) and (2) can be treated in a routined way elaborated in Ref. [1]. The terms in the curly brackets and those proportional to Ω in Eqs. (1) and (2) need special attention and are treated as in Appendix A. Finally, the γ -dependent SO coupling terms only involve first order space derivatives and are treated in a routined fashion.

The presented programs are straightforward modifications of the basic programs published in Refs. [1,2]. The three components of the wave function are accommodated by introducing a new index “L” in addition to the space indices in the corresponding arrays, i.e., the wave-function components are represented by CP(L,I,J) in 2D and CP(L,I) in 1D, where L = 1, 2, 3 stands for the spin components $j = +1, 0$, and -1 , respectively, and I and J denote discretized space points. The time propagation with respect to different terms in Eqs. (1) and (2) are dealt with in different subroutines. The kinetic energy term ($\nabla^2/2$) is treated using the Crank–Nicolson discretization in subroutines COEF, LUX, and LUY in 2D, and in 1D in subroutines COEF and LU, as in Refs. [1,2]. The potential term and the diagonal part of the nonlinear terms in square brackets, proportional to c_0 and c_2 , are treated in the subroutine CALCNU. The off-diagonal part of the nonlinear terms in curly brackets in Eqs. (1) and (2), explicitly considered in Eq. (A.1), is treated in the subroutine HERM, while the different SO coupling terms are treated in the subroutine SO. The conservation of the normalization and magnetization, as defined by Eqs. (A.6) and (A.7), is implemented in the subroutine RENORM. The energies are calculated in the subroutine ENERGY and expectation values of the condensate’s cloud sizes are calculated in the subroutine RADIUS in 2D and LENGTH in 1D. The different modules (Subroutines and Functions) of the programs in 1D and 2D and their respective usage are presented in Table 1.

A description of the input parameters together with the output files with description is given in Table 2. Most of the parameters have the same meaning as in our previously published programs and the reader can refer to Ref. [6] for details. For an efficient performance on computers with multiple CPU cores, the programs have been parallelized using the OpenMP library. The number of threads (CPU cores) to be used is declared by the parameter NTHREADS, which should be equal to or less than the total number of available threads. If NTHREADS is set to zero, then all available CPU cores will be used. The parameters NSTP, NPAS, and NRUN denote different numbers of time iterations, the total number of iterations being the sum of these. If NSTP is different from zero, then the program starts the time propagation using an analytic initial function defined in the subroutine INITIALIZE. If NSTP is zero, the program reads an initial wave function for the calculation from input files, i.e., from the previously calculated files named `<code>-wave-fun-fin.txt`. In this way one can perform the imaginary- or real-time propagation with a pre-calculated wave function. The supplied programs use the pre-defined value NSTP = 10 and use an analytic wave function as the initial state. When using a pre-calculated wave function by setting NSTP to zero, the number of space grid points N (1D) and NX, NY (2D) employed previously should match exactly the number of points used in the current program. The supplied programs assume equal numbers of space step points in both imaginary- and real-time propagation. The parameter OPT_SO selects the type of SO coupling. In 1D, OPT_SO = 1, 2, 3 uses the SO couplings $\gamma p_x \Sigma_x$, $\gamma p_x \Sigma_y$, and $\gamma p_x \Sigma_z$, respectively. In 2D, OPT_SO = 1, 2, 3 uses Rashba, Dresselhaus, and an equal mixture of Rashba and Dresselhaus SO couplings, respectively. The choice OPT_SO = 0 corresponds to no SO coupling. The parameters MAG_0, GAM0 (GAMMA0 in 1D) and OMEGA0 denote magnetization, the strength of SO coupling γ and that of Rabi coupling Ω , respectively. The parameter OPT_PROP selects the type of time propagation: imaginary-time (1) and real-time (2). All input data are conveniently placed at the beginning of each program, as before [5]. After changing the input data in a program a recompilation is required. The output files are conveniently named such that their contents can be easily identified, following the naming convention introduced in Ref. [5]. For example, a file named `<code>-out.txt`, where `<code>` denotes imaginary- (im) or real-time (re) propagation, represents the general output file

Table 1
Different modules of the 1D and 2D programs and their usage.

	Module name	Type	Usage
1D	IMRE1D	MAIN	Main program
	INITIALIZE	Subroutine	Calculates or reads the initial function
	CALC_TRAP	Subroutine	Calculates the confining trap
	COEF	Subroutine	Calculates the coefficients of the Crank–Nicolson method
	SO	Subroutine	Propagates the spin–orbit coupling term in time
	LU	Subroutine	Crank–Nicolson time propagation
	HERM	Subroutine	Propagates the off-diagonal terms of the GP equation and the Rabi coupling term in time
	CALCNU	Subroutine	Propagates the diagonal parts of the GP equation in time
	LENGTH	Subroutine	Calculates the length of the condensate
	RENORM	Subroutine	Fixes the normalization and magnetization
	ENERGY	Subroutine	Calculates the energy of the condensate
SIMP	Function	Performs integration by Simpson's rule	
2D	IMRE2D	MAIN	Main program
	INITIALIZE	Subroutine	Calculates or reads the initial function
	CALC_TRAP	Subroutine	Calculates the confining trap
	COEF	Subroutine	Calculates the coefficients of the Crank–Nicolson method
	SO	Subroutine	Propagates the spin–orbit coupling term in time
	LUX	Subroutine	Crank–Nicolson time propagation in x variable
	LUY	Subroutine	Crank–Nicolson time propagation in y variable
	HERM	Subroutine	Propagates the off-diagonal terms of the GP equation and the Rabi coupling term in time
	CALCNU	Subroutine	Propagates the diagonal parts of the GP equation in time
	INTEGRATE	Function	Performs double integration in x and y
	RADIUS	Subroutine	Calculates the radius of the condensate
	RENORM	Subroutine	Fixes the normalization and magnetization
	ENERGY	Subroutine	Calculates the energy of the condensate
	SIMP	Function	Performs integration by Simpson's rule

Table 2
Name and description of input parameters and output files.

	Name	Description
Input	NSTP, NPAS, NRUN	Number of time iterations, NSTP = 0 reads initial function, NSTP > 0 calculates initial function
	N, NX, NY	Number of space integration points
	NTHREADS	Number of threads used
	C_0, C_2	Nonlinear input parameters (c_0, c_2)
	OPT_SO	Selects the type of SO coupling
	DX, DY	Space discretization steps
	OPT_PROP	Selects the type of time propagation imaginary-time (=1) or real-time (=2)
	OPT_ST	Selects initial function in 2D
	MAG_0	Magnetization (m)
	GAMO	Strength of SO coupling (γ)
OMEGA0	Strength of Rabi coupling (Ω)	
Output	im-out.txt	Input parameters, energy and size
	im-den-<desc>.txt	<desc>=ini initial & =fin final density
	im-phase.txt	phase of a 2D wave function
	im-wave-fun-<desc>.txt	<desc>=ini initial & =fin final wave function
	im-den-rad-<desc>.txt	<desc>=ini initial & =fin final radial density (2D)

containing input data, space and time steps DX, DY and DT, nonlinearity c_0 and c_2 , energy, size, etc. The files `<code>-den-ini.txt` and `<code>-den-fin.txt` contain the initial and final components and total densities in different columns. In 1D (2D) these densities are functions of one (two) space point(s) placed in the first (and second) column(s) of the respective files. The densities ρ_{+1} , ρ_0 , ρ_{-1} , and ρ can be found in the successive columns. The file `<code>-den-rad-fin.txt` stores the final linear radial densities ρ_{+1} , ρ_0 , ρ_{-1} , and ρ for the 2D GP equation in different columns, while the space points are saved in the first column. The file `<code>-wave-fun-fin/ini.txt` contains the final/initial complex wave functions. For a 2D BEC, the file `<code>-phase.txt` contains the phases of the component wave functions in different columns, since the phase is important for the study of angular momentum of the respective states. The printing of some of these files, such as the initial density and wave function, is commented out in the programs, so that the supplied programs do not print these.

We provide below the beginning of the 1D program where the parameters are defined so that the reader can easily identify the different statements there. The 2D program is quite similar.

```
! Begin selection of input parameters
MODULE COMM_DATA
! SELECT # OF SPACE POINTS N AND # OF TIME ITERATIONS NSTP, NPAS & NRUN
! USE NSTP = 0 TO READ WAVE FUNCTION FILE FROM STDIN: < im-wave-fun-fin.txt
```

```

INTEGER, PARAMETER :: N = 640, NX = N-1, NX2 = N/2
INTEGER, PARAMETER :: NSTP = 10, NPAS = 1000000, NRUN = 100000
! INTEGER, PARAMETER :: NSTP = 0, NPAS = 1000000, NRUN = 100000
! Number of OpenMP threads, less than or equal to the maximum available cores.
INTEGER, PARAMETER :: NTHREADS = 0 ! NTHREADS = 0 uses all available cores
REAL (8), PARAMETER :: Pi = 3.14159265358979D0
END MODULE COMM_DATA
!*****
MODULE SPIN_PARS
USE COMM_DATA, ONLY : PI
!***** SELECT POLAR (C_2 > 0) OR FERROMAGNETIC (C_2 < 0) BEC *****
! REAL (8), PARAMETER :: C_0 = 241.d0, C_2 = 7.5d0 ! Anti-ferromagnetic
REAL (8), PARAMETER :: C_0 = 885.d0, C_2 = -4.1d0 ! Ferromagnetic
END MODULE SPIN_PARS
!*****
MODULE GPE_DATA
USE COMM_DATA, ONLY : N, Pi
USE SPIN_PARS, ONLY : C_0, C_2
!*****
!*** SELECT OPTION FOR SO COUPLING AND STRENGTH GAMMA
! INTEGER,PARAMETER :: OPT_SO = 0; REAL (8), PARAMETER :: GAMMA0 = .00D0 ! No SO coupl.
INTEGER,PARAMETER :: OPT_SO = 1; REAL (8), PARAMETER :: GAMMA0 = .500D0 ! Sigma_x p_x
! INTEGER,PARAMETER :: OPT_SO = 2; REAL (8), PARAMETER :: GAMMA0 = .500D0 ! Sigma_y p_x
! INTEGER,PARAMETER :: OPT_SO = 3; REAL (8), PARAMETER :: GAMMA0 = .500D0 ! Sigma_z p_x
!*****
REAL (8), PARAMETER :: DX = 0.05D0 ! SELECT SPACE STEP DX
!!SELECT OPTION FOR PROPAGATION: IMAGINARY-TIME or REAL-TIME
INTEGER, PARAMETER :: OPT_PROP = 1; REAL (8), PARAMETER :: DT = DX*DX*0.10D0 ! IMAG
! INTEGER, PARAMETER :: OPT_PROP = 2; REAL (8), PARAMETER :: DT = DX*DX*0.05D0 ! REAL
!!SELECT PARAMETERS OF MODEL
REAL (8), PARAMETER :: MAG_0 = .400000D0, ACCUR=1.D-6 ! Magnetization
REAL (8), PARAMETER :: OMEGA0 = .00D0 ! Rabi and SO coupling
!*****
! End selection of input parameters

```

Below we provide a sample output file re-out.txt for the 2D program for the readers to familiarize.

```

REAL-TIME PROPAGATION
# of threads = 16

RASHBA SO coupling, GAMMA = 0.5000000000000000
RABI coupling Omega = 0.0000000000000000E+000
Nonlinearity C_0 = 482.000000, C_2 = 15.000000
OPT_ST = 0.7500000000000000

Space and time steps: DX = 0.10000, DY = 0.10000, DT = 0.2500E-03
# of space steps: NX = 161, NY = 161
# of time steps: NSTP = 0, NPAS = 80000, NRUN = 10000

```

	RAD(1)	RAD(2)	RAD(3)	Energy	MAG
NSTP iter.:	3.469	2.194	3.469	8.1969	0.0000
NPAS iter.:	3.468	2.193	3.468	8.1969	-0.0000
NRUN iter.:	3.469	2.195	3.469	8.1969	-0.0000

```

Clock Time: 129 seconds
CPU Time: 2048 seconds

```

Another crucial aspect for the execution of imaginary-time propagation to find the lowest-energy ground state is a proper choice of initial state with right symmetry property as the final state. Different types of states can be obtained for different sets of parameters. Without SO coupling, the solution is of the Gaussian type and a Gaussian function should be chosen as the initial state. For small Rashba or Dresselhaus SO-coupling strength γ ($\gamma \lesssim 0.75$), the lowest-energy circularly-symmetric state of the three components of a quasi-2D SO-coupled anti-ferromagnetic (polar) spin-1 BEC is of the $(-1, 0, +1)$ or $(+1, 0, -1)$ type, where the numbers in the parenthesis represent the angular momentum of the vortices in the center of the components $j = +1, 0, -1$, respectively, with the

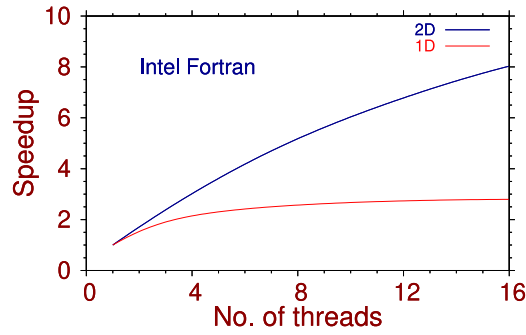


Fig. 1. Speedup of execution on a 20-core machine with two Intel Xeon E5-2650 processors (2×10 CPU cores) versus the number of threads used, for a quasi-1D and quasi-2D BEC for a typical run. The size of the space grid in 1D is 1000 and in 2D it is 200×200 . The programs were compiled using the Intel Fortran compiler v. 19.0.4.243.

negative sign representing an anti-vortex. For a ferromagnetic spin-1 quasi-2D BEC these states are of the type $(0, \pm 1, \pm 2)$ for Rashba and Dresselhaus SO-couplings, respectively, in agreement with the consideration of Ref. [26]. For an equal mixture of Rashba and Dresselhaus SO couplings, for small γ , the lowest-energy ferromagnetic BEC states are of the Gaussian type without any vortices; the anti-ferromagnetic BEC states are of the stripe type with periodic 1D modulation in density. For an efficient computation, the vortices or anti-vortices are introduced in the initial wave functions when required. The vortex of angular momentum L is imprinted by taking the initial state as a Gaussian multiplied by the factor $(x + iy)^L$, and an anti-vortex by the factor $(x - iy)^L$. For large SO-coupling strength γ ($\gamma \gtrsim 0.75$), the density of the lowest-energy ground state of the three components of an SO-coupled spinor BEC exhibits different patterns (not considered in this paper). The initial states in the 2D program have to be chosen accordingly. A stripe pattern is generated by multiplying an initial Gaussian state by $\sin(\gamma x)$ and $\cos(\gamma x)$. The user can change the initial state for a SO-coupled BEC by choosing the value of the parameter OPT_ST. For $\gamma < \text{OPT_ST}$ the states of type $(\mp 1, 0, \pm 1)$ and $(0, \pm 1, \pm 2)$ are chosen in anti-ferromagnetic and ferromagnetic phases, the upper (lower) sign corresponds to Rashba (Dresselhaus) SO coupling. In the anti-ferromagnetic phase, for $\gamma > \text{OPT_ST}$, the stripe states are chosen as the initial state. However, to reproduce the results reported in this paper there is no need to change the parameter OPT_ST. For an equal mixture of Rashba and Dresselhaus SO couplings Gaussian-type initial states are appropriate for the ferromagnetic phase and stripe states for the anti-ferromagnetic phase.

If the imaginary-time propagation is performed, the programs run either by using an initial analytic input function (if NSTP is not set to zero), or by employing a pre-calculated wave function (if NSTP is set to zero). The real-time propagation can successfully work only if initialized with a meaningful wave function, usually assuming that NSTP = 0 is set, and that the program will read a pre-calculated wave function by the earlier performed imaginary-time propagation. The calculation is essentially done within the NPAS time iteration loop. Another NSTP time iteration is accommodated to verify if the results converged by comparing the energies and sizes after NPAS and NSTP iterations. The source programs spin-SO-imre1d-omp.f90 (1D) and spin-SO-imre2d-omp.f90 (2D) are located in the directory src within the corresponding package directory BEC-GP-SPINOR-OMP. A README.md file, included in the corresponding root directory, explains the procedure to compile and run the programs in more detail using a makefile. In the beginning of each program the compilation commands are given for GNU, Intel, PGI, and Oracle (former Sun) Fortran compilers. They can be compiled by the make command using the provided makefile in the corresponding package root directory. Otherwise, they can be compiled by the commands given at the beginning of the programs using Intel, GNU, PGI, and Oracle FORTRAN compilers. The examples of produced output files can be found in the directory output, although some large density files are omitted, to reduce the software package size.

We conclude this section demonstrating the efficiency of our OpenMP parallelization scheme using the Intel compiler on a machine with 2×10 CPU cores in Fig. 1, where we plot the speedup versus number of threads. The speedup for n threads is defined as the ratio of clock time for a single thread to that for n threads. From Fig. 1 we find the clock time reduces with the increase of the number of threads, thus making the execution more efficient in a multi-core machine.

4. Numerical results

All calculations reported below were performed with the predefined space and time steps DX and DT in the programs: in 1D DX = 0.05, DT = DX*DX*0.1 (imaginary time) and DT = DX*DX*0.05 (real time); in 2D DX = 0.1, DT = DX*DX*0.1 (imaginary time) and DT = DX*DX*0.025 (real time). To increase the accuracy of calculation, the space step(s) DX and DY should be reduced and the total number of space discretization points N, NX, and NY increased proportionally.

The parameters of the GP equation c_0 and c_2 are taken from the following realistic experimental situations. For the ferromagnetic BEC the quasi-1D trap parameters are $l = 2.41927 \mu\text{m}$, $l_{yz} = 0.54 \mu\text{m}$ and we use the following parameters of ^{87}Rb atoms: $N = 10,000$, $a_0 = 101.8a_B$, $a_2 = 100.4a_B$, where a_B is the Bohr radius. Consequently, $c_0 \equiv 2N(a_0 + 2a_2)l/3l_{yz}^2 \approx 885$ and $c_2 \equiv 2N(a_2 - a_0)l/3l_{yz}^2 \approx -4.1$. For the quasi-1D anti-ferromagnetic BEC we use the trap parameters $l = 4.7 \mu\text{m}$, $l_{yz} = 1.05 \mu\text{m}$ following parameters of ^{23}Na atoms: $N = 10,000$, $a_0 = 50.00a_B$, $a_2 = 55.01a_B$. Consequently, $c_0 \approx 241$ and $c_2 \approx 7.5$. For the quasi-2D ferromagnetic BEC we use the following parameters of ^{87}Rb atoms: $N = 100,000$, $a_0 = 101.8a_B$, $a_2 = 100.4a_B$, [27] $l_z = 2.0157 \mu\text{m}$. Consequently, $c_0 \equiv 2N\sqrt{2\pi}(a_0 + 2a_2)/3l_z \approx 1327.5$ and $c_2 \equiv 2N\sqrt{2\pi}(a_2 - a_0)/3l_z \approx -6.15$. For the quasi-2D anti-ferromagnetic BEC we use the following parameters of ^{23}Na atoms: $N = 100,000$, $a_0 = 50.00a_B$, $a_2 = 55.01a_B$, [28] $l_z = 2.9369 \mu\text{m}$. Consequently, $c_0 \approx 482$ and $c_2 \approx 15$.

Although we will calculate the lowest-energy ground state by imaginary-time propagation, it is possible that in some cases for larger values of SO coupling strength γ (not considered in this paper) the imaginary-time approach may converge to a nearby excited state instead of the lowest-energy ground state for certain initial states. The symmetry, such as parity, of the initial state plays a vital role.

Table 3

Convergence of energies of harmonically trapped 1D and 2D spin-1 ferromagnetic (ferro) and anti-ferromagnetic (polar) BECs with change of space steps DX and DY. The parameters in 1D: $c_0 = 885$, $c_2 = -4.1$ (ferro) and $c_0 = 241$, $c_2 = 7.5$ (polar). The parameters in 2D: $c_0 = 1327.5$, $c_2 = -6.15$ (ferro), $c_0 = 482$, $c_2 = 15$ (polar). The SO-coupled results in 1D refer to the coupling $\gamma p_x \Sigma_x$ with $\gamma = 0.5$ and those in 2D correspond to the Rashba coupling with $\gamma = 0.5$. The parameters considered here are appropriate for a Rb and Na BEC with trap parameters of Ref. [25].

DX (=DY)	1D (ferro) energy	1D (ferro) % error	1D (polar) energy	1D (polar) % error	2D (ferro) energy	2D (ferro) % error	2D (polar) energy	2D (polar) % error
0.4	36.01167	0.00058	15.12364	0.00066	13.59737	0.00176	8.19636	0.00660
0.2	36.01146	0	15.12354	0	13.59759	0.00015	8.19687	0.00037
0.1	36.01146	0	15.12354	0	13.59761	0	8.19690	0
< 0.05	36.01146	0	15.12354	0	13.59761	0	8.19690	0

Table 4

Energies of harmonically-trapped spin-1 anti-ferromagnetic (polar) and ferromagnetic (ferro) quasi-1D and quasi-2D BECs for different values of magnetization m . In the quasi-2D case we consider only the circularly-symmetric states. The parameters in 1D: $c_0 = 241$, $c_2 = 7.5$ (polar) and $c_0 = 885$, $c_2 = -4.1$ (ferro), space step DX = 0.05, time step DT = 0.00025. The parameters in 2D: $c_0 = 482$, $c_2 = 15$ (polar) and $c_0 = 1327.5$, $c_2 = -6.15$ (ferro), space steps DX = DY = 0.1, time step DT = 0.0005. The SO-coupled (SO-cpld) results in 1D refer to the coupling $\gamma p_x \Sigma_x$ with $\gamma = 0.5$ and those in 2D correspond to the Rashba or Dresselhaus coupling with $\gamma = 0.5$. For systems with large nonlinearities the numerically obtained energy E_{num} lies between the TF [29] and variational (var) limit: $E_{\text{TF}} < E_{\text{num}} < E_{\text{var}}$. The parameters considered here are appropriate for a Rb and Na BEC with trap parameters of Ref. [25].

	m	1D spinor	1D spinor [25]	1D spinor var	1D spinor TF	1D SO-cpld $\gamma = 0.5$	2D spinor	2D spinor var	2D spinor TF	2D SO-cpld $\gamma = 0.5$
Polar	0	15.2485	15.2485	15.7522	15.2239	15.1235	8.3605	8.8155	8.2577	8.1969
	0.1	15.2514	15.2514				8.3617			
	0.2	15.2599	15.2599				8.3652			
	0.3	15.2743	15.2743				8.3710			
	0.4	15.2945	15.2945				8.3793			
	0.5	15.3209	15.3209				8.3900			
	0.6	15.3537	15.3537				8.4033			
Ferro	0	36.1365	36.1365	37.3574	36.1243	36.0115	13.7420	14.5364	13.6723	
	0.0468	36.1365					13.7420			13.5976
	0.1	36.1365	36.1365				13.7420			
	0.2	36.1365	36.1365				13.7420			
	0.3	36.1365	36.1365				13.7420			
	0.4	36.1365	36.1365				13.7420			
	0.5	36.1365	36.1365				13.7420			
0.6	36.1365	36.1365				13.7420				

An even-parity (odd-parity) initial state will find the lowest-energy state with even (odd) parity. For small γ there are only a few possibilities of symmetry and this problem does not appear for the results reported in this paper. But for larger γ , and especially in the quasi-2D case, there are states with many possibilities of symmetry and it may not be easy to know, a priori, the symmetry of the lowest-energy state. Hence, for large γ , it is advised to repeat the calculation with different initial states, so as to be sure that the converged state is indeed the lowest-energy ground state. In fact, any numerically computed final wave function, obtained with the same number of space points, can be used as the initial state for a new calculation.

Before we illustrate our results, we now study in Table 3 the convergence of our calculational scheme in 1D and 2D for SO-coupled ferromagnetic and polar BECs employing the above-mentioned parameters in 1D and 2D upon the reduction of space steps DX and (= DY) from 0.4 to 0.05. In this Table we display the energies, viz. Eq. (5), and the respective percentage numerical errors for four different sets of parameters in 1D and 2D. We see that upon a reduction of space step the energy value rapidly converges. The result for energy with space step 0.4 is already very accurate and the result remains unchanged to five significant figures after the decimal point for

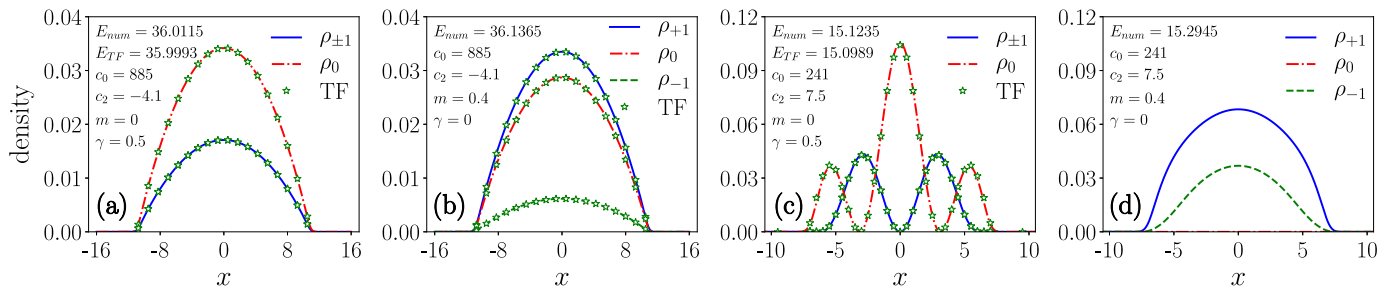


Fig. 2. Numerically calculated component density $\rho_j(x)$ (lines) and energy E of a quasi-1D harmonically trapped SO-coupled ferromagnetic BEC with nonlinearities $c_0 = 885$, $c_2 = -4.1$ and (a) $\gamma = 0.5$ and (b) $m = 0.4$, $\gamma = 0$, compared with the analytic TF result (chain of symbols). The same for an anti-ferromagnetic BEC with nonlinearities $c_0 = 241$, $c_2 = 7.5$ and (c) $\gamma = 0.5$ and (d) $m = 0.4$, $\gamma = 0$. The SO-coupling is $\gamma p_x \Sigma_x$ with $\gamma = 0.5$ in all cases. All densities are calculated by imaginary-time propagation employing Gaussian input functions. All results reported in this paper are in dimensionless units, as outlined in Section 2.

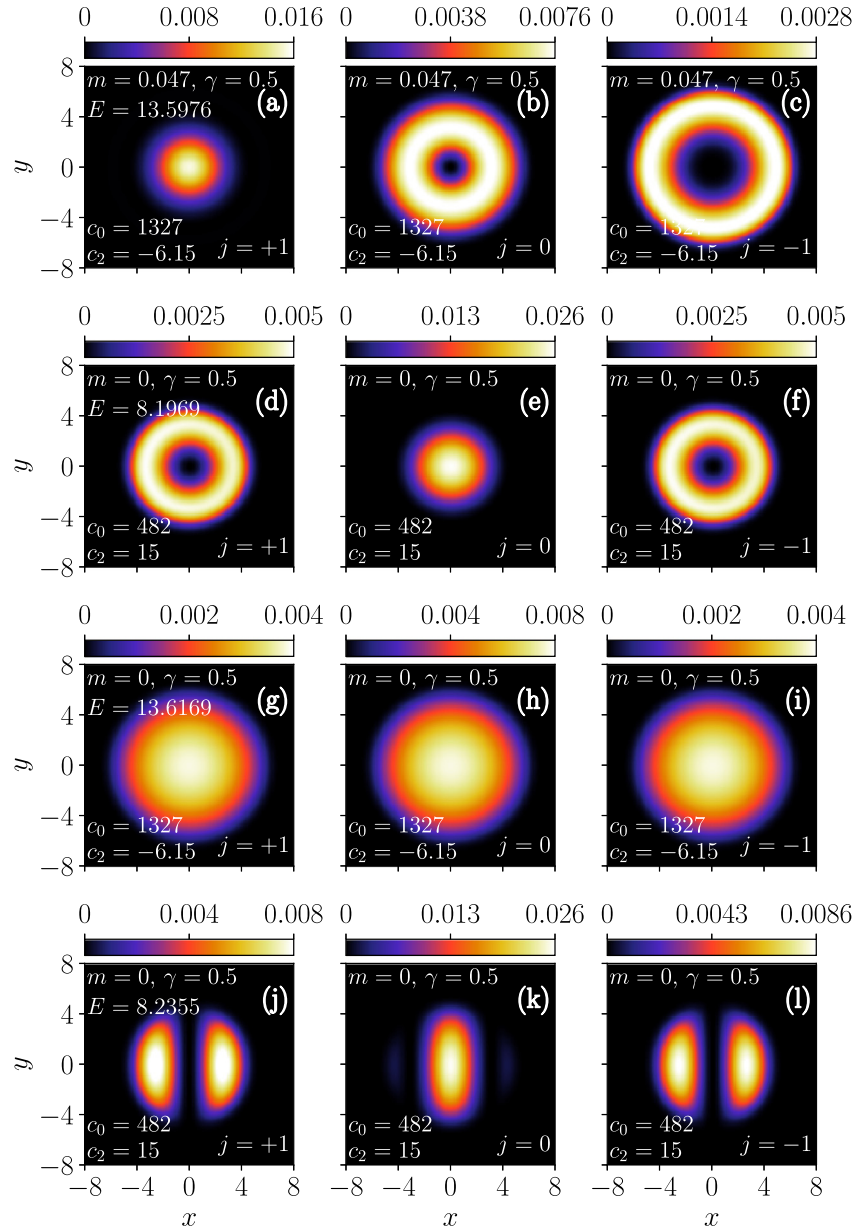


Fig. 3. Contour plots of numerically calculated component densities $\rho_j(x, y)$ for (a) $j = +1$, (b) $j = 0$, and (c) $j = -1$ of a quasi-2D harmonically trapped Rashba or Dresselhaus SO-coupled ferromagnetic BEC with nonlinearities $c_0 = 1327.5$, $c_2 = -6.15$, the SO-coupling strength $\gamma = 0.5$. (d)-(f) A Rashba or Dresselhaus SO-coupled anti-ferromagnetic BEC with nonlinearities $c_0 = 482$, $c_2 = 15$, and $\gamma = 0.5$. (g)-(i) A ferromagnetic BEC with $c_0 = 1327.5$, $c_2 = -6.15$, $\gamma = 0.5$ for an equal mixture of Rashba and Dresselhaus SO couplings. (j)-(l) An anti-ferromagnetic BEC with $c_0 = 482$, $c_2 = 15$, $\gamma = 0.5$ for an equal mixture of Rashba and Dresselhaus SO couplings. The numerical energies are displayed in plots (a), (d), (g), and (j).

space steps 0.1 and 0.05 both in 1D and 2D. In the following we will present results of our study with space steps 0.05 and 0.1 in 1D and 2D, respectively. The accuracy increases as the space-step is reduced, but a reduced value of space step requires a larger number of time iterations for convergence. Hence, it is computationally more economic to use a large space step.

In Table 4 we show the energy, viz. Eq. (1), of an anti-ferromagnetic and a ferromagnetic BEC in quasi-1D and quasi-2D traps for different values of magnetization m . For the quasi-2D trap, we consider only the circularly-symmetric states. In 2D the energies are the same for both Rashba and Dresselhaus SO couplings, although the underlying wave functions are different. The analytic TF and variational energies are also displayed, for comparison, as well as those from Ref. [25]. In the case of a ferromagnetic BEC without SO coupling, the energies are independent of m values, whereas in the anti-ferromagnetic case the dependence on m exists, as can be seen. In both cases the analytic TF and variational energies are independent of m . For condensates with large densities as in Table 4, where the TF results are reliable, the actual energies are larger than the corresponding TF values [29]. On the other hand, the variational energies are always larger than the actual energies. Hence for large nonlinearities, as we see in Table 4, the variational and TF energies define the two bounds for the actual, numerically calculated energy. In Table 4 we also present the numerically calculated energies for the SO-coupled BECs in 1D and 2D for $\gamma = 0.5$.

We show the numerically calculated and the TF component densities $\rho_j(\mathbf{x})$ of a quasi-1D harmonically trapped ferromagnetic SO-coupled BEC for $c_0 = 885$ and $c_2 = -4.1$, with $\gamma = 0.5$ in Fig. 2(a) and $m = 0.4$, $\gamma = 0$ in Fig. 2(b), along with the corresponding

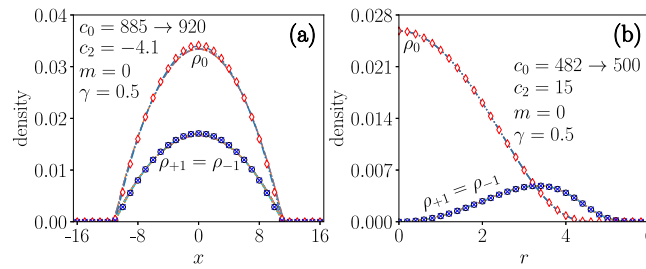


Fig. 4. (a) Numerically calculated component densities of the quasi-1D SO-coupled ferromagnetic BEC of Fig. 2(a) with $c_0 = 885$, $c_2 = -4.1$, $\gamma = 0.5$ during the real-time evolution at times $t = 50, 100, 150, 200$ (full lines), using the imaginary-time wave function as the initial state, compared with the converged imaginary-time densities shown in Fig. 2(a) (chain of symbols). The parameter c_0 was changed from 885 to 920 at $t = 0$. (b) Numerically calculated radial component densities of the quasi-2D anti-ferromagnetic Dresselhaus SO-coupled BEC of Fig. 3(d)–(f) with $c_0 = 482$, $c_2 = 15$, $\gamma = 0.5$ during the real-time evolution at times $t = 50, 100, 150, 200$ (full lines), using the imaginary-time wave function as the initial state, compared with the converged imaginary time densities (chain of symbols). The parameter c_0 was changed from 482 to 500 at $t = 0$.

energy values given by Eq. (5). All the states reported here are the lowest-energy ground states for a given set of parameters, obtained by imaginary-time propagation. The same quantities are shown for an anti-ferromagnetic BEC with $c_0 = 241$ and $c_2 = 7.5$, with $\gamma = 0.5$ in Fig. 2(c) and with $m = 0.4$, $\gamma = 0$ in Fig. 2(d). The SO coupling in both cases is of type $\gamma p_x \Sigma_x$ with $\gamma = 0.5$. These nonlinear parameters c_0 and c_2 were considered previously in Ref. [25]. These states are calculated with the analytic initial functions, included by setting $NSTP \neq 0$.

We now exhibit the density of a Rashba SO-coupled quasi-2D spinor BEC for $\gamma = 0.5$. The BEC components develop distinct angular momentum structure in this case. To illustrate this, we display in Fig. 3(a)–(c) the contour plots of densities of a ferromagnetic Rashba or Dresselhaus SO-coupled BEC. In Fig. 3(d)–(f) the corresponding contour plots of an anti-ferromagnetic Rashba or Dresselhaus SO-coupled BEC are shown, while Fig. 3(g)–(i) displays the same for a ferromagnetic BEC for an equal mixture of Rashba and Dresselhaus couplings. In Fig. 3(j)–(l) the plots are shown for an anti-ferromagnetic BEC, also for an equal mixture of Rashba and Dresselhaus couplings. In all cases the nonlinearities c_0 and c_2 are the same as in Table 3. The components $j = +1, 0$ and -1 in Fig. 3(a)–(c) have angular momentum $0, \pm 1, \pm 2$, respectively, for Rashba and Dresselhaus SO couplings. On the other hand, the components in Fig. 3(d)–(f) have angular momentum $\mp 1, 0, \pm 1$, respectively, for Rashba and Dresselhaus SO couplings. The angular momenta of the spinor components were found from the contour plot of the phases of the corresponding wave functions (not explicitly considered in this paper).

Finally, we demonstrate the dynamical stability of the imaginary-time results using the real-time propagation for a large interval of time. Using the converged imaginary-time wave function as the initial state, the real-time calculation is initiated after introducing a small perturbation, by changing the value of c_0 at $t = 0$ by a small amount. First we consider the quasi-1D SO-coupled ferromagnetic spinor BEC of Fig. 2(a) and perform a real-time simulation for 200 units of time by changing c_0 from 885 to 920. The component densities at times $t = 50, 100, 150$, and 200 are plotted in Fig. 4(a). The imaginary-time converged results (chain of symbols) are also shown, for comparison. Next we consider a quasi-2D anti-ferromagnetic Rashba SO-coupled spinor BEC with $c_0 = 482$, $c_2 = 15$, $\gamma = 0.5$, viz. Fig. 3(d)–(f), which is taken as initial state and a real-time propagation is performed for 200 units of time upon changing c_0 from 482 to 500 at $t = 0$. The radial component densities are plotted at times $t = 50, 100, 150$, and 200 in Fig. 4(b) together with the converged imaginary-time density (chain of symbols). The fact that all component densities in Fig. 4(a) and (b) for a quasi-1D and a quasi-2D BEC over a large interval of time are stable during the real-time propagation demonstrates the dynamical stability of the condensate.

5. Summary

We have presented efficient OpenMP FORTRAN programs for solving the GP equation for a three-component spin-1 spinor BEC and used these to calculate the densities and energies for various values of system parameters. Different SO and Rabi coupling terms can be included in the programs. We provide two sets of programs: one for a quasi-1D BEC and the other for a quasi-2D BEC. Each of these programs is capable of executing both the imaginary- and the real-time propagation. The imaginary-time propagation programs yield appropriate results in agreement with variational approximation in all cases [21,30]. We use the split-step Crank-Nicolson discretization to implement time propagation, relying on our earlier OpenMP FORTRAN programs of Ref. [6]. The GP equation can be solved by imaginary- or real-time propagation with an analytic wave function or a pre-calculated numerical wave function as the initial state. We stress that the convergence with one initial state could be much faster than with another initial state, and tailoring the input wave function using an analytic or a previously calculated numerical wave function is always an advantage. We have also presented the results for density and energy of different states and compared these with analytic variational and TF approximate results.

Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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Appendix A. Detailed numerical procedure

All terms in Eqs. (1) and (2), except the last terms containing explicit complex conjugation, have the form of a conventional diagonal GP equation for a three-component BEC, whose solution procedure employing the split-step method is well known. The last non-diagonal terms in Eqs. (1) and (2), as well as the Rabi coupling terms proportional to $\tilde{\Omega}$ require special attention. In explicit matrix notation, the split-step equation that takes into account the last terms of Eqs. (1) and (2), together with the Rabi coupling terms proportional to $\tilde{\Omega}$, can be written as

$$i\partial_t \begin{pmatrix} \psi_{+1}(\mathbf{r}, t) \\ \psi_0(\mathbf{r}, t) \\ \psi_{-1}(\mathbf{r}, t) \end{pmatrix} = \mathbf{A} \begin{pmatrix} \psi_{+1}(\mathbf{r}, t) \\ \psi_0(\mathbf{r}, t) \\ \psi_{-1}(\mathbf{r}, t) \end{pmatrix}, \quad \text{where } \mathbf{A} = \begin{pmatrix} 0 & a & 0 \\ a^* & 0 & b \\ 0 & b^* & 0 \end{pmatrix}, \quad (\text{A.1})$$

and $a = c_2\psi_{-}\psi_0 + \tilde{\Omega}$, $b = c_2\psi_0^*\psi_{+} + \tilde{\Omega}$. The real eigenvalues of the Hermitian matrix \mathbf{A} are $\lambda_1 = C = \sqrt{|a|^2 + |b|^2}$, $\lambda_2 = 0$, and $\lambda_3 = -C$, while the corresponding eigenvectors are $v_1 = (v_{11}, v_{12}, v_{13})^T = (a, C, b^*)^T$, $v_2 = (v_{21}, v_{22}, v_{23})^T = (b, 0, -a^*)^T$, and $v_3 = (v_{31}, v_{32}, v_{33})^T = (a, -C, b^*)^T$, respectively. For a sufficiently small time step Δ , the solution of Eq. (A.1) is given by

$$\begin{pmatrix} \psi_{+1}(\mathbf{r}, t + \Delta) \\ \psi_0(\mathbf{r}, t + \Delta) \\ \psi_{-1}(\mathbf{r}, t + \Delta) \end{pmatrix} = \mathbf{V} \begin{pmatrix} e^{-i\Delta\lambda_1} & 0 & 0 \\ 0 & e^{-i\Delta\lambda_2} & 0 \\ 0 & 0 & e^{-i\Delta\lambda_3} \end{pmatrix} \mathbf{V}^{-1} \begin{pmatrix} \psi_{+1}(\mathbf{r}, t) \\ \psi_0(\mathbf{r}, t) \\ \psi_{-1}(\mathbf{r}, t) \end{pmatrix}, \quad (\text{A.2})$$

where

$$\mathbf{V} \equiv \begin{pmatrix} v_{11} & v_{21} & v_{31} \\ v_{12} & v_{22} & v_{32} \\ v_{13} & v_{23} & v_{33} \end{pmatrix} = \begin{pmatrix} a & b & a \\ C & 0 & -C \\ b^* & -a^* & b^* \end{pmatrix}, \quad \mathbf{V}^{-1} = \frac{1}{2C^2} \begin{pmatrix} a^* & C & b \\ 2b^* & 0 & -2a \\ a^* & -C & b \end{pmatrix}. \quad (\text{A.3})$$

In Eq. (A.2) the right-hand-side is considered known, since it is expressed in terms of the wave-function values at time t , and thus the wave function is easily propagated to time $t + \Delta$. In case of larger spins, if the matrix \mathbf{A} of larger dimension cannot be analytically diagonalized, it can be diagonalized numerically by one of the many available subroutine packages.

When we consider the SO coupling terms proportional to $\tilde{\gamma}$, they can be also evaluated at time t using the known wave-function values, and the corresponding split-step equations can be solved to propagate the wave functions to time $t + \Delta$. For example, in case of the $\gamma p_x \Sigma_x$ coupling in 1D, these are performed via

$$\psi_{\pm 1}(\mathbf{r}, t + \Delta) = \psi_{\pm 1}(\mathbf{r}, t) - \Delta \tilde{\gamma} \partial_x \psi_0(\mathbf{r}, t), \quad (\text{A.4})$$

$$\psi_0(\mathbf{r}, t + \Delta) = \psi_0(\mathbf{r}, t) - \Delta \tilde{\gamma} [\partial_x \psi_{+1}(\mathbf{r}, t) + \partial_x \psi_{-1}(\mathbf{r}, t)]. \quad (\text{A.5})$$

In Eqs. (A.4) and (A.5) the right-hand-side at time t is known and hence the wave-function values at time $t + \Delta$ can be obtained from those at time t . All SO coupling terms are treated in the same fashion.

The simultaneous maintenance of the normalization and magnetization m , viz. Eq. (4), during the time propagation, given by Eqs. (4), is done following the procedure of Ref. [31], by rescaling the wave-function components after each time step Δ according to $\psi_j \rightarrow d_j \psi_j$, where

$$d_0 = \frac{\sqrt{1 - m^2}}{\sqrt{N_0 + \sqrt{4(1 - m^2)N_{+1}N_{-1} + m^2N_0^2}}}, \quad d_1 = \frac{\sqrt{1 + m - d_0^2N_0}}{\sqrt{2N_{+1}}}, \quad d_{-1} = \frac{\sqrt{1 - m - d_0^2N_0}}{\sqrt{2N_{-1}}}, \quad (\text{A.6})$$

and $N_j = \int d\mathbf{r} \rho_j(\mathbf{r}, t)$. However, when the SO coupling does not commute with Σ_z , we do not impose the condition of conservation of magnetization and the rescaling is done according to

$$d_0 = d_{+1} = d_{-1} = \frac{1}{\sqrt{N_0 + N_{+1} + N_{-1}}}. \quad (\text{A.7})$$

Appendix B. Supplementary data

Supplementary material related to this article can be found online at <https://doi.org/10.1016/j.cpc.2020.107657>. It contains analytic variational and Thomas-Fermi approximations developed for the calculations presented in this paper.

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